

Table of Contents

List of Acronyms and Symbols	ix
Abstract	xiii
Deutsche Kurzzusammenfassung	xvii
1 Introduction	1
1.1 Related work	4
1.2 Contributions and outline	10
2 Preliminaries	15
2.1 System model	15
2.2 Stability definitions	18
2.3 Integral quadratic constraints	19
3 Analysis of maximum sampling intervals under reverse average dwell-time conditions	23
3.1 Recap: Maximum sampling interval analysis without reverse average dwell-time conditions	24
3.2 Stability analysis based on maximum sampling intervals and reverse average dwell-time conditions	26
3.3 Summary	36
4 A framework for event-triggered control based on $\mathcal{L}_p$ norms	37
4.1 A small-gain perspective	38
4.2 $\mathcal{L}_p$ gain based sampling	41
4.3 Relationship with existing triggering rules	49
4.4 Numerical example	54
4.5 Summary	57
5 Event-triggered control based on integral quadratic constraints	59
5.1 Setup	60
5.2 Sampling based on integral quadratic constraints	62
5.3 Numerical example	65

5.4	Summary	67
6	Dynamic self-triggered control for nonlinear systems using hybrid Lyapunov functions	71
6.1	Concept of the proposed self-triggered control approach	72
6.2	Specific dynamic self-triggered control mechanisms with input-to-state stability guarantees	84
6.3	Regional results for bounded disturbances	88
6.4	Numerical Example	93
6.5	Summary	99
7	Conclusions and outlook	101
7.1	Summary and conclusions	101
7.2	Outlook	103
A	Verifying Assumptions 1, 2 and 5 for linear systems	107
B	Remaining Proofs	111
B.1	Chapter 4	111
B.2	Chapter 5	112
B.3	Chapter 6	114
	Bibliography	123
	Publications of the Author	138